

MATRIX ALGEBRA

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MATRICES

Definition:- A collection of numbers arranged in rows and columns is said to be an array, A matrix is a rectangular array of numbers closed in addition, subtraction, multiplication, and division.

We represent a matrix by $A = [a_{ij}]_{m \times n}$, $i = 1(1)m$, $j = 1(1)n$.

$$\text{i.e. } \therefore A = \begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{bmatrix}$$

Diagonal matrix:-

$A = [a_{ij}]$ is such that $a_{ij} = 0 \forall i \neq j$

$$\text{i.e. } A = \text{diag}[d_1, d_2, \dots, d_n]$$

Eg. $A = \begin{bmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & 0 \\ 0 & 0 & a_{33} \end{bmatrix}$ is a 3×3 diagonal matrix.

Scalar matrix:-

$$A = [a_{ij}] \Rightarrow \begin{cases} a_{ij} = 0 \forall i \neq j \\ a_{ij} = k \forall i = j, k \in \mathbb{R} \end{cases}$$

Eg $A = \begin{bmatrix} a & 0 & 0 \\ 0 & a & 0 \\ 0 & 0 & a \end{bmatrix}$

Triangular matrix:- If every element above or below the leading diagonal of a square matrix is zero, then the matrix is called a triangular matrix.

Upper triangular matrix:-

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix}$$

Lower triangular matrix:-

$$\begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Equality of matrices:- Two matrices A and B of the same order are said to be equal, if and only if the corresponding elements are equal.

Multiplication of matrix by a scalar:- Matrix multiplication is associative and distributive but not commutative.

$$A = [a_{ij}]_{m \times n}$$

$$kA = \begin{bmatrix} ka_{11} & ka_{12} & \dots & ka_{1n} \\ ka_{21} & ka_{22} & \dots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \dots & ka_{mn} \end{bmatrix} = [ka_{ij}]_{m \times n}$$

Addition of Matrices:-

$$A = [a_{ij}]_{m \times n} \quad B = [b_{ij}]_{m \times n}$$

$$A+B = [a_{ij} + b_{ij}]$$

Matrix addition is commutative, associative and distributive.

Note:- Only a square matrix can have a determinant.

Transpose of a matrix:-

$$A = [a_{ij}]_{m \times n}$$

$$A^T = [a_{ji}]_{n \times m}$$

$$(1) (A^T)^T = A.$$

$$(2) (A+B)^T = A^T + B^T.$$

$$(3) (AB)^T = B^T A^T.$$

Symmetric and skew-symmetric matrices:-

For a symmetric mtr. A , $a_{ij} = a_{ji} \forall i, j$.

For a skew-symmetric mtr A , $a_{ij} = -a_{ji} \forall i \neq j$
 $= 0 \quad \forall i = j$.

Ex.1. If A be any matrix, s.t. AA^T and $A^T A$ are symmetric.

Sol. $(AA^T)^T = (A^T)^T (A)^T = AA^T$

$$(A^T A)^T = (A)^T (A^T)^T = A^T A$$

Hence AA^T and $A^T A$ both are symmetric.

Ex.2. If A and B are both symmetric, then AB is symmetric iff A and B commute.

Sol.

$$A^T = A, \quad B^T = B$$

$$(AB)^T = B^T A^T$$

$$= BA$$

$$= AB \text{ iff } A \text{ and } B \text{ commute.}$$

This shows $(AB)^T$ is symmetric.

Ex.3. s.t. A^2 is symmetric, if A is either symmetric or skew-symmetric.

Sol.

A^2 exists only if A is ^{square} mtr.

Let $A = [a_{ij}]$, $i, j = 1, 2, \dots, n$. Then

$$A^2 = [c_{ij}], \quad i, j = 1, 2, \dots, n, \text{ where,}$$

$$c_{ij} = \sum_{k=1}^n a_{ik} a_{kj}$$

Case I:- When A is symmetric, then $a_{kj} = a_{jk}$.

$$\therefore c_{ij} = \sum_{k=1}^n a_{ik} a_{jk}$$

$$\therefore c_{ji} = \sum a_{jk} a_{ik} \text{ ; on interchanging } i \text{ and } j.$$

\therefore Clearly, $c_{ij} = c_{ji}$, $\therefore A^2$ is symmetric.

Case II:- When A is skew-symmetric, then $a_{kj} = -a_{jk}$.

$$\therefore c_{ij} = \sum_{k=1}^n a_{ik} (-a_{jk}) = - \sum_{k=1}^n a_{ik} a_{jk}$$

$$\text{so that } c_{ji} = \sum a_{jk} a_{ik} \text{ , on interchanging } i \text{ and } j.$$

$$\text{Clearly, } c_{ij} = c_{ji}$$

\therefore Hence A^2 is again symmetric.

$\therefore A^2$ is symmetric if A is either symmetric or skew-symmetric.

Ex. 4. S.T. all positive integral powers of a symmetric matrix are symmetric.

Sol.

$$A' = A$$

$$(A^n)' = (AA \dots n \text{ times})', n \text{ be a positive integer}$$

$$= A'A' \dots n \text{ times}$$

$$= AA \dots n \text{ times as } A' = A$$

$$= A^n; \text{ hence } A^n \text{ is symmetric.}$$

Ex. 5. S.T. all positive odd (even) integral powers of a skew-symmetric matrix are skew-symmetric (symmetric).

Sol.

$$A' = -A$$

$$(A^n)' = (AA \dots n \text{ times})'$$

$$= A'A' \dots n \text{ times}$$

$$= (-A)(-A) \dots n \text{ times as } A' = -A.$$

$$= (-1)^n A^n$$

$$= \begin{cases} A^n, & n = \text{even} \quad \therefore A^n \text{ is symmetric.} \\ -A^n, & n = \text{odd} \quad \therefore A^n \text{ is skew-symmetric.} \end{cases}$$

Ex. 6. If A is symmetric (skew-symmetric), show that $B'AB$ is symmetric (skew-symmetric).

Sol.

Case I:- $A^T = A$ $(B'AB)' = (B)'A'(B)'$
 $= B'AB$

Case II:- $A^T = -A$, $(B'AB)' = -B'AB$

Ex.7. If A and B are symmetric (skew-symmetric), s.t. $A+B$ is symmetric (skew-symmetric).

Ex.8. If A be any ^{sq.} matrix, s.t. $A+A'$ is symmetric and $A-A'$ is skew-symmetric.

Sol.

$$(A+A')' = (A') + (A)' = A' + A = (A+A')$$

$$(A-A')' = (A') - (A)' = A' - A = -(A-A')$$

Ex.9. If A, B are symmetric, s.t. $AB+BA$ is symmetric and $AB-BA$ is skew-symmetric.

Ex.10. Show that every square matrix can be uniquely expressed as the sum of a symmetric and a skew-symmetric matrix.

Sol.

$$A = \frac{1}{2}(A+A') + \frac{1}{2}(A-A')$$

$$(A+A')' = A' + (A)' = A' + A$$

$$(A-A')' = A' - A = -(A-A')$$

$\therefore A+A'$ is symmetric and $A-A'$ is skew-symmetric.

Conjugate and Triangulated of matrix:-

A matrix obtained by replacing each element of a mtrx A by its complex conjugate is called the conjugate mtrx of A and is denoted by \bar{A} .

A matrix is said to be real iff $\bar{A} = A$.

$(\bar{A})'$ is called triangulated matrix of A .

Hermitian and Skew-Hermitian matrices:-

$$A^* = [a_{ij}] \text{ is Hermitian iff } a_{ij} = \bar{a}_{ji} \forall i, j$$

$$= \bar{a}_{ii} \forall i=j$$

i.e. every diagonal element of a Hermitian mtrx is real.

e.g. $\begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix}$, $\begin{bmatrix} 4 & 1-i \\ 1+i & 2 \end{bmatrix}$ are the examples of Hermitian mtrx.

$$A = [a_{ij}] \text{ is skew-Hermitian iff } a_{ij} = -\bar{a}_{ji} \forall i, j.$$

i.e. Every diagonal element of a skew-hermitian mtrx is either purely imaginary or zero.

e.g. $\begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 1-i \\ -1-i & 2i \end{bmatrix}$

Q. Show that $A = \begin{bmatrix} 3 & 1+2i \\ 1-2i & 2 \end{bmatrix}$ is Hermitian.

Sol. \bar{A} = conjugate of $A = \begin{bmatrix} 3 & 1+2i \\ 1+2i & 2 \end{bmatrix}$

and $A^* = (\bar{A})'$ transpose of $\bar{A} = \begin{bmatrix} 3 & 1+2i \\ 1-2i & 2 \end{bmatrix}$

Clearly, $A^* = A$; hence A is Hermitian.

Note:- The ~~above~~ above all results of symmetric and skew-symmetric matrices are true if we replace symmetric mtrx by

Hermitian matrix and skew-symmetric mtr. by skew-Hermitian mtr.

Note:- 1. Every square mtr. can be uniquely represented as the sum of a hermitian and a skew-hermitian matrix.

2. Every square mtr. can be uniquely expressed as $P+iQ$, where P and Q are hermitian.

3. If A is Hermitian (skew-hermitian) mtr., then iA is a skew-hermitian (Hermitian) mtr.

Polynomials in square matrix with scalar coefficients:-

The algebra of polynomials in one square mtr A with scalar coefficients is the same as the algebra of ordinary polynomials.

For example, two parallel identities are:

$$x^2 - (\alpha + \beta)x + \alpha\beta \equiv (x - \alpha)(x - \beta)$$

$$A^2 - (\alpha + \beta)A + \alpha\beta I \equiv (A - \alpha I)(A - \beta I)$$

More generally, if

$$x^n + p_1 x^{n-1} + \dots + p_{n-1} x + p_n \equiv (x - \alpha_1)(x - \alpha_2) \dots (x - \alpha_n)$$

$$\text{then } A^n + p_1 A^{n-1} + \dots + p_{n-1} A + p_n I \equiv (A - \alpha_1 I)(A - \alpha_2 I) \dots (A - \alpha_n I)$$

Ex.1. Find the scalar solutions of the mtr equation $A^2 - 5A + 7I = 0$, and show that $\begin{bmatrix} 3 & 1 \\ -2 & 2 \end{bmatrix}$ is a non-scalar solution.

Sol. Consider the algebraic equation

$$x^2 - 5x + 7 = 0;$$

$$x = \frac{5 \pm i\sqrt{3}}{2}$$

Hence the scalar solutions are $A = \frac{1}{2}(5 \pm i\sqrt{3})I$, where $I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$

$$\text{i.e. } A = \begin{bmatrix} \frac{1}{2}(5 + i\sqrt{3}) & 0 \\ 0 & \frac{1}{2}(5 + i\sqrt{3}) \end{bmatrix}$$

2nd part:-

$$\text{If } A = \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}, \text{ then } A^2 = \begin{bmatrix} 8 & 5 \\ -5 & 3 \end{bmatrix}$$

$$A^2 - 5A = \begin{bmatrix} 8 & 5 \\ -5 & 3 \end{bmatrix} - 5 \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}$$

$$= -7 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$= -7I$$

Hence $\begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix}$ is a non-scalar solution.

Idempotent Matrix

Definition:- A square matrix A such that $A^2 = A$ is called idempotent. If $A^T = A$ and $A^2 = A$, then the square matrix A is called symmetric idempotent.

Theorem:- Every non-singular idempotent matrix is an identity matrix.

Proof:- A matrix A is said to be non-singular or regular if $|A| \neq 0$.
As A is idempotent so $A^2 = A$ or $AA = A$.

Now, a square matrix B of the same order as A , such that $AB = BA = I$, is called the inverse matrix of A and is denoted by A^{-1} and exists as A is non-singular.

$$\begin{aligned} A^{-1}(AA) &= A^{-1}A \\ \Rightarrow IA &= I \\ \Rightarrow A &= I. \end{aligned}$$

Theorem:- If A and B are idempotent matrices, then AB is idempotent if A and B commute.

Proof:- $A^2 = A$, $B^2 = B$

$$\begin{aligned} (AB)^2 &= (AB)(AB) \\ &= A(BA)B \\ &= A(AB)B \\ &= (AA)(BB) \\ &= A^2B^2 = AB \text{ as } A \text{ and } B \text{ commute, i.e. } AB = BA. \end{aligned}$$

Theorem:- $\therefore AB$ is idempotent.

If A is idempotent and $A+B=I$, then B is idempotent and $AB=BA=0$.

Proof:- since $A+B=I$, $\therefore B=(I-A)$

$$\begin{aligned} B^2 &= (I-A)(I-A) \\ &= I - A - A + A^2 \\ &= I - A \quad [\because A^2 = A] \\ &= B. \end{aligned}$$

$\therefore B$ is an idempotent matrix.

2nd part:-

$$A+B=I$$

$$A(A+B)=AI$$

$$A^2+AB=A$$

$$A+AB=A$$

$$\therefore AB=0$$

Similarly $BA=0$.

Theorem:- Show that the matrix A defined as

$A = I_n - X(X'X)^{-1}X'$ is a symmetric and idempotent matrix.

Sol.

$$\begin{aligned} A &= I_n - X(X'X)^{-1}X' \\ &= I_n - \{XX^{-1}\} \{X'\}^{-1}X' \\ &= I_n - (I_n)(I_n) \\ &= I_n - I_n = 0 \end{aligned}$$

Therefore $A' = A$ and $A^2 = A$.

Nilpotent Matrix:-

Definition:- If A be a nilpotent mtr such that $A^m = 0$, where m is positive integer, then A is called a nilpotent matrix.

If m be the least positive integer for which $A^m = 0$, then A is said to be a nilpotent matrix of index m . Thus a square mtr $A \ni A^m = 0$, but $A^{m-1} \neq 0$ is a nilpotent mtr of order m , m being a positive integer.

Involuntary Matrix:-

Definition:- A square mtr A is such that
 $A^2 = I$ or, $(I+A)(I-A) = 0$
is called involuntary. Clearly I is involuntary.

Ex. Show that $A = \begin{bmatrix} ab & b^2 \\ -a^2 & -ab \end{bmatrix}$ is nilpotent.

Sol. $A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

Orthogonal matrix:-

Definition:- A square mtr A is said to be orthogonal if
 $A'A = I = AA'$.

Note:- When A is orthogonal $|A|^2 = 1$, $|A| = \pm 1$. If $|A|$ is equal to 1, then A is called a proper mtr.

Theorem:- If A and B are n -square orthogonal matrices, then AB and BA are orthogonal matrices.

Proof:- Since A and B are orthogonal matrices, we have
 $AA' = I$ and $BB' = I$

$$\begin{aligned} (AB)(AB)' &= (AB)(B'A') \\ &= A(BB')A' \\ &= AA' \\ &= I \end{aligned}$$

$\therefore AB$ is orthogonal, similarly BA is also orthogonal.

Ex.1. S.T. the mtr $A = \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$ is orthogonal.

Sol. $AA' = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$; hence A is orthogonal.

Ex.2. If A is real skew-symmetric matrix such that $A^2 + I = 0$. Show that A is orthogonal.

Sol. $A = -A'$
 $AA = -AA'$
 $A^2 = -AA'$
 $-I = -AA'$
 $\therefore AA' = I$
 $\therefore A$ is orthogonal.

Unitary matrix:-

Definition:- A square matrix A is called unitary if

$$A^*A = I = AA^*$$

If A is real then $A^* = A'$, so that A is unitary if

$$A'A = AA' = I$$

Ex. Show that $A = \begin{bmatrix} \frac{1}{2}(1+i) & -\frac{1}{2}(1-i) \\ \frac{1}{2}(1+i) & \frac{1}{2}(1-i) \end{bmatrix}$ is unitary mtr.

Sol. $A = \frac{1}{2} \begin{bmatrix} 1+i & 1-i \\ 1+i & 1-i \end{bmatrix}$

$$A^* = \frac{1}{2} \begin{bmatrix} 1+i & 1-i \\ -1-i & 1+i \end{bmatrix}$$

$$AA^* = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I$$

$\therefore A$ is unitary.

Trace (or spur) of a square matrix:-

Definition:- The sum of the elements of the principal diagonal of a square matrix is called the trace (or, spur, a german word) of the matrix.

Thus if $A = [a_{ij}]$ be a square matrix of order n , then

$$\text{trace } A = a_{11} + a_{22} + a_{33} + \dots + a_{nn} = \sum_{i=1}^n a_{ii}$$

Remark:- For the identity mtr I_n , trace $I_n = n$.

Ex. 1. Show that for any sq. mtr A, B :-

(i) Trace $(kA) = k \text{ trace } (A)$, k being a scalar.

(ii) Trace $(KA + B) = k \text{ trace } (A) + \text{trace } (B)$.

Sol. (i) $A = [a_{ij}]_{n \times n}$. Then $kA = [ka_{ij}]_{n \times n}$

$$\begin{aligned} \text{Trace } (kA) &= \sum_{i=1}^n ka_{ii} \\ &= k \text{Trace } (A). \end{aligned}$$

(ii) $A = [a_{ij}]_{n \times n}$, $B = [b_{ij}]_{n \times n}$

$$KA + B = [ka_{ij} + b_{ij}]_{n \times n}$$

$$\begin{aligned} \text{Trace } (KA + B) &= \sum_{i=1}^n (ka_{ii} + b_{ii}) \\ &= k \sum_{i=1}^n a_{ii} + \sum_{i=1}^n b_{ii} \\ &= k \text{trace } (A) + \text{trace } (B) \end{aligned}$$

e.g. If trace $(A) = 20$, trace $(B) = -8$, then trace $(A+B) = 12$.

Ex. 2. Show that $\text{trace } A' = \text{trace } A$.

Sol. Let $A = [a_{ij}]_{n \times n}$, $A' = [a'_{ij}]_{n \times n} = [a_{ji}]_{n \times n}$

therefore when $i=j$, we have $\text{trace}(A) = \text{trace}(A')$.

Ex. 3. Show that $\text{trace}(AB) = \text{trace}(BA)$, if AB and BA co-exist.

Sol.

$$A = [a_{ij}]_{m \times n} \quad B = [b_{ij}]_{n \times m}$$

$$AB = [c_{ij}]_{m \times m} \quad ; \quad c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$$\begin{aligned} \therefore \text{trace}(AB) &= \sum_{i=1}^m c_{ii} \\ &= \sum_{i=1}^m \sum_{k=1}^n a_{ik} b_{ki} \end{aligned}$$

$$BA = [d_{ij}]_{n \times n}$$

$$d_{ij} = \sum_{k=1}^m b_{ik} a_{kj}$$

$$\begin{aligned} \therefore \text{trace}(BA) &= \sum_{i=1}^n d_{ii} \\ &= \sum_{i=1}^n \sum_{k=1}^m b_{ik} a_{ki} \\ &= \sum_{k=1}^m \sum_{i=1}^n b_{ki} a_{ik} \quad , \text{interchanging } i \text{ and } k. \\ &= \sum_{i=1}^n \sum_{k=1}^m a_{ik} b_{ki} \end{aligned}$$

$$\therefore \text{trace}(AB) = \text{trace}(BA).$$

Ex. 4. S.T. $\text{trace}(AA') \geq 0$.

Sol.

$$A = [a_{ij}]_{m \times n}, \quad A' = [a'_{ij}]_{n \times m}$$

$$AA' = [c_{ij}]_{m \times m}, \quad c_{ij} = \sum_{k=1}^n a_{ik} a'_{kj}$$

$$\begin{aligned} \therefore \text{trace}(AA') &= \sum_{i=1}^m c_{ii} \\ &= \sum_{i=1}^m \sum_{k=1}^n a_{ik} a'_{ki} \\ &= \sum_{i=1}^m \sum_{k=1}^n (a_{ik})^2 \quad \text{as } a_{ik} = a'_{ki} \end{aligned}$$

Ex. 5. S.T. $\text{trace}(C'AC) \geq 0$, if C is an orthogonal matrix.

Sol.

$$\begin{aligned} \text{trace}(C'AC) &= \text{trace}\{C'(AC)\} \\ &= \text{trace}\{(AC)C'\} \quad , \text{ as } \text{trace } AB = \text{trace } BA. \\ &= \text{trace}\{A(CC')\} \quad , \text{ as } C \text{ is orthogonal matrix.} \\ &= \text{trace}(A). \end{aligned}$$

The adjoint of a square matrix:-

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}, \text{Adj} A = \begin{bmatrix} A_{11} & A_{12} & \dots & A_{1n} \\ A_{12} & A_{22} & \dots & A_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ A_{1n} & A_{2n} & \dots & A_{nn} \end{bmatrix}$$

Theorem:- If A is a square matrix, then
 $A(\text{adj} A) = (\text{adj} A) \cdot A = |A| \cdot I.$

Sol. We have

The (i, j) th element of the product $A \cdot (\text{adj} A)$
 $=$ Product of the i th row of A and j th column of $\text{adj} A$
 $= a_{i1} A_{j1} + a_{i2} A_{j2} + \dots + a_{in} A_{jn}$
 $= \begin{cases} 0 & \text{if } i \neq j \\ |A| & \text{if } i = j \end{cases}$

Thus in the product, only the diagonal elements exist and each is equal to $|A|$ while all other elements are zero, so that

$$\begin{aligned} A \cdot (\text{adj} A) &= \begin{bmatrix} |A| & 0 & 0 & \dots & 0 \\ 0 & |A| & 0 & \dots & 0 \\ 0 & 0 & |A| & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & |A| \end{bmatrix} \\ &= |A| \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \end{bmatrix} \\ &= |A| \cdot I. \end{aligned}$$

Similarly, $(\text{adj} A) \cdot A = |A| \cdot I.$

Corollary 1:- If $|A| \neq 0$, we have

$$|A| \cdot |A \cdot \text{adj} A| = \begin{bmatrix} |A| & 0 & \dots & 0 \\ 0 & |A| & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & |A| \end{bmatrix} = |A|^n$$

$$\therefore |A \cdot \text{adj} A| = |A|^{n-1}$$

Corollary 2:- If $|A| \neq 0$, then

$$A \left(\frac{1}{|A|} \text{adj} A \right) = I = \left(\frac{1}{|A|} \text{adj} A \right) A.$$

Singular matrix:- A sq. matrix is said to be singular if its determinant is zero.

Theorem:- If A and B are n -square matrices, then

$$\text{Adj } AB = \text{Adj } A \cdot \text{Adj } B.$$

Sol. We have $AB \cdot (\text{adj } AB) = |AB| \cdot I = (\text{adj } AB) \cdot AB$

$$\begin{aligned} \text{Now, } AB(\text{adj } B)(\text{adj } A) &= A(B \cdot \text{adj } B)(\text{adj } A) \\ &= A \cdot (|B| \cdot I)(\text{adj } A) \\ &= |B| \cdot (A \cdot \text{adj } A) \\ &= |B| |A| \cdot I \\ &= |AB| \cdot I \end{aligned}$$

$$\begin{aligned} \text{Also, } (\text{adj } B)(\text{adj } A)AB &= (\text{adj } B)[\text{adj}(A) \cdot A]B \\ &= (\text{adj } B)|A| \cdot IB \\ &= |A|[(\text{adj } B) \cdot B] \\ &= |A| \cdot |B| \cdot I \\ &= |AB| \cdot I. \end{aligned}$$

$$\therefore \text{Adj}(AB) = \text{Adj}(A) \text{Adj}(B).$$

Ex.1. Show that $\text{Adj } A' = (\text{adj } A)'$

Sol. Obviously, the matrices $\text{adj } A'$ and $(\text{adj } A)'$ both will be of the same order as A . Now,

$$\begin{aligned} \Rightarrow (i, j)\text{th element of } \text{Adj } A' &= \text{the co-factor of } (j, i)\text{th element of } A' \text{ in} \\ &\quad \text{the determinant } |A'|. \\ &= \text{the co-factor of } (i, j)\text{th element of } A \text{ in} \\ &\quad \text{the determinant } |A| \\ &= (j, i)\text{th element of } \text{Adj } A. \end{aligned}$$

$$\therefore \text{Adj } A' = (\text{adj } A)'$$

Ex.2. Show that every skew-symmetric mtr of odd order is singular.

Solution:- Let A be a skew-symmetric matrix of order n , where n is odd. Since A is skew-symmetric, we have

$$A' = -A.$$

$$\begin{aligned} |A'| &= |-A| \\ &= (-1)^n |A| \end{aligned}$$

$$= -|A|, \text{ where } n \text{ is odd and } |A'| = |A|$$

$$\therefore |A| = -|A|$$

$$\therefore 2|A| = 0$$

$$\Rightarrow |A| = 0.$$

Hence a skew-symmetric mtr of odd order is singular.

WORKED EXAMPLES:-

1. Let A be a non-singular sq. mtr of order 3. If B is the mtr obtained from A by adding 3-multiple of its first row to its second row, then the value of $\det(2A^{-1}B)$ is
(A) 8 (B) 3 (C) 6 (D) 2

Sol. (D) $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$

$$|A| \neq 0,$$

$$A \sim B = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 3a_{11} + a_{21} & 3a_{12} + a_{22} & 3a_{13} + a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

Since A and B are equivalent so $|A| = |B|$

$$\begin{aligned} \therefore \det(2A^{-1}B) &= 2|A^{-1}||B| \\ &= 2 \cdot \frac{1}{|A|} \cdot |B| \\ &= 2 \dots \end{aligned}$$

2. Let \underline{u} be a unit column vector and $A = I - 2\underline{u}\underline{u}^T$. Then A^{-1} is
(A) $I - 2\underline{u}\underline{u}^T$ (B) $I + 2\underline{u}\underline{u}^T$ (C) $2\underline{u}\underline{u}^T - I$ (D) $4\underline{u}\underline{u}^T$.

Sol. $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 2 \cdot [1 \ 1 \ 1] \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

$$= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = I - 2\underline{u}\underline{u}^T$$

3. Let P, Q, R be matrices of order $3 \times 5, 5 \times 7, 7 \times 3$ respectively. The number of scalar additions required to compute $P(QR)$ is
(A) 114 (B) 126 (C) 128 (D) 138.

Sol. We have to calculate $P(QR)$.

Q and R is of order 5×7 and 7×3 respectively. When we multiply it we have to make 6 scalar addition for each entry so 5 column in Q and 3 rows in R column we multiply Q and R .

We do $6 \times 5 \times 3 = 90$ addition further QR is of 5×3 matrix.

Similarly when we multiply P to QR we perform $4 \times 3 \times 3$ addition

$$\therefore \text{Total no. of additions} = 90 + 36 = 126.$$

4. If A is a square matrix and $A - \frac{1}{2}I$ and $A + \frac{1}{2}I$ are orthogonal, prove that A is skew-symmetric & $A^2 = -\frac{3}{4}I$.

Sol. Since $A - \frac{1}{2}I$ is orthogonal,

$$\text{So, } (A - \frac{1}{2}I)(A - \frac{1}{2}I)^T = I$$

$$\text{or, } (A - \frac{1}{2}I)(A' - \frac{1}{2}I) = I$$

$$\text{or, } AA' - \frac{1}{2}IA' - \frac{1}{2}AI + \frac{1}{4}I^2 = I$$

$$\text{or, } AA' - \frac{1}{2}A' - \frac{1}{2}A = \frac{3}{4}I \quad \text{--- (1)}$$

Similarly since $A + \frac{1}{2}I$ is orthogonal, we have

$$AA' + \frac{1}{2}A' + \frac{1}{2}A = \frac{3}{4}I \quad \text{--- (2)}$$

$$\therefore \text{ (1) \& (2) gives } A' + A = 0$$

$$\text{(1) - (2)} \quad \Rightarrow A' = -A$$

$\therefore A$ is skew-symmetric.

$$\text{(1) + (2) gives } 2AA' = \frac{3}{2}I$$

$$\therefore 2A(-A) = \frac{3}{2}I$$

$$\therefore A^2 = -\frac{3}{4}I.$$

5. If $A = \begin{bmatrix} 1+i & 2-3i & 2 \\ 3-4i & 4+5i & 1 \\ 5 & 3 & 3-i \end{bmatrix}$. Find the conjugate of matrix A ?

Sol. $\bar{A} = \begin{bmatrix} 1-i & 2+3i & 2 \\ 3+4i & 4-5i & 1 \\ 5 & 3 & 3+i \end{bmatrix}$

6. Let P and Q be two $n \times n$ nonzero matrices $\exists P+Q=0$, then show that,

(i) P is non-singular

(ii) $P = Q^T$

(iii) $P = Q^{-1}$

(iv) $\text{Rank}(P) = \text{Rank}(Q)$.

Sol. Given that P and Q are two $n \times n$ matrices such that $P+Q=0$.

$$\therefore P+Q=0 \Rightarrow P = -Q$$

$$\Rightarrow |P| = |Q|$$

$$\Rightarrow |P| \neq 0 \text{ iff } |Q| \neq 0$$

i.e. P is non-singular iff Q is non-singular.

If Q is non-singular then Q^{-1} exists. $|Q^{-1}| = |Q^T| = |Q|$

$$\therefore P = Q^T = Q^{-1}.$$

But if $P+Q=0$ then $\text{Rank}(P) = \text{Rank}(Q)$.

Example 1 - $P = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $Q = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$

Then $P+Q=0$ and $\text{Rank}(P) = \text{Rank}(Q)$.

7. Show that all $n \times n$ symmetric matrices over F form a vector space of dimension $\frac{n(n+1)}{2}$ over F . What is the dimension of the space of skew-symmetric matrices?

Sol.

Let $A = (a_{ij})$ be an $n \times n$ symmetric mtr.
 Then $a_{ij} = a_{ji} \forall i \neq j$. Thus the number of independent entries are $a_{ij} (i < j)$ and $a_{ij} (1 \leq i \leq n)$ and there are $\frac{n(n-1)}{2} + n = \frac{n(n+1)}{2}$ in number.

Hence the space has dimension $\frac{n(n+1)}{2}$.

For a skew-symmetric mtr, $a_{ij} = 0, 1 \leq i \leq n, \forall i = j$ and $a_{ij} = -a_{ji}$.
 Thus the number of LIN entries are $\frac{n(n-1)}{2}$ which is also the dimension of the space of skew-symmetric matrices.

8. (a) If A is a real skew-symmetric mtr and $A^2 + I = 0$, then s.t. A is orthogonal.

(b) If H is Hermitian mtr, what kind of mtr is e^{iH} ?

Sol. (a) Let A be the real skew-symmetric mtr.

then $A^T = -A$.

Also we have $A^2 + I = 0$.

We have $A^T A = (-A)(A) = I$.

$\therefore A$ is orthogonal.

(b) Let H is Hermitian mtr. $H^* = H$.

For any mtr M , $(e^M)^* = e^{M^*}$

Let $e^{iH} = A$

Then $A^* A = (e^{iH})^* \cdot e^{iH} = I$.

Hence e^{iH} is unitary matrix.

Inverse or Reciprocal of a matrix:-

Let A be a square matrix of order n . Then the mtr B of order n , if it exists, such that

$$AB = BA = I_n,$$

is called the inverse or reciprocal of A and is denoted by A^{-1} .

$$A^{-1} = \left(\frac{\text{Adj}A}{|A|} \right) \cdot I, \text{ provided } |A| \neq 0.$$

Corollary:- We have $|A| |A^{-1}| = |AA^{-1}| = |I| = 1$

$$\text{Hence } |A^{-1}| = |A|^{-1}.$$

Theorem:- the inverse of a matrix is unique.

Sol. If possible let B and C be two inverses of the same mtr A , then by definition

$$AB = BA = I$$

$$AC = CA = I$$

$$\therefore C(AB) = CI = C$$

$$\therefore (CA)B = IB = B$$

$\therefore C = B$, \therefore the inverse is unique.

Theorem:- A square matrix A has an inverse if and only if $|A| \neq 0$, i.e. only a non-singular matrix has an inverse.

Proof:- the condition is necessary. Let B be the inverse of the mtr A .

$$\text{then } AB = I$$

$$\text{so, that } |A||B| = |I| = 1$$

$$\therefore |A| \neq 0.$$

\therefore the condition is sufficient.

Let $|A| \neq 0$, we assume that $B = \frac{\text{Adj}A}{|A|}$

$$\therefore AB = A \left(\frac{\text{Adj}A}{|A|} \right)$$

$$= \frac{1}{|A|} \cdot (A \cdot \text{Adj}A)$$

$$= \frac{|A| \cdot I}{|A|} = I$$

Similarly $BA = I$.

$\therefore AB = BA = I$, \therefore Hence A has an inverse.

Ex. 1 find A^{-1} when $A = \begin{bmatrix} 1 & 0 & -1 \\ 3 & 4 & 5 \\ 0 & 6 & -7 \end{bmatrix}$.

Sol. $|A| = 20$; $\text{Adj} A = \begin{bmatrix} 2 & 6 & 4 \\ 21 & -7 & -8 \\ -18 & 6 & 4 \end{bmatrix}$

$$\text{Hence } A^{-1} = \frac{\text{Adj} A}{|A|} = \begin{bmatrix} \frac{2}{20} & \frac{6}{20} & \frac{4}{20} \\ \frac{21}{20} & \frac{-7}{20} & \frac{-8}{20} \\ \frac{-18}{20} & \frac{6}{20} & \frac{4}{20} \end{bmatrix}$$

Ex. 2. Show that the inverse of a regular symmetric (hermitian) matrix is symmetric (hermitian).

Sol. Let A be symmetric, so that $A = A'$

$$\& AA^{-1} = I = A^{-1}A$$

Since $I = I'$, so, $A^{-1}A = (A^{-1}A)'$

$$\begin{aligned} AA^{-1} &= (A^{-1}A)' \\ &= A'(A^{-1})' \\ &= A(A^{-1})' \end{aligned}$$

$$\therefore A^{-1} = (A^{-1})'$$

$\therefore A^{-1}$ is symmetric.

2nd Part:- Let A be hermitian, so that

$$A^* = A$$

$$A^{-1}A = AA^{-1} = I$$

$$\therefore (A^{-1}A)^* = I^* = I = (AA^{-1})$$

$$\& A^*(A^{-1})^* = AA^{-1}$$

$$\therefore A(A^{-1})^* = AA^{-1}$$

$$\therefore (A^{-1})^* = A^{-1}$$

$\therefore A^{-1}$ is hermitian.

Ex. 3. find the inverse of $A = \begin{bmatrix} 0 & 1 & 2 & 2 \\ -1 & 1 & 2 & 3 \\ 2 & 2 & 2 & 3 \\ -2 & 3 & 3 & 3 \end{bmatrix}$.

Sol.

$$A = I \times A$$

$$\begin{bmatrix} 0 & 1 & 2 & 2 \\ 1 & 1 & 2 & 3 \\ 2 & 2 & 2 & 3 \\ 2 & 3 & 3 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 1 & 3 \\ 0 & 2 & 1 & 3 \\ 1 & 3 & 0 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A \quad \begin{cases} c_1' \leftrightarrow c_2 - c_1 \\ c_3' \leftrightarrow c_4 - c_3 \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 2 & 1 & 3 \\ 1 & 1 & -1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A \quad \begin{cases} R_2' \leftrightarrow R_3 - R_2 \\ R_4' \leftrightarrow R_4 - R_3 \end{cases}$$

$$\begin{bmatrix} 1 & 1 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & -1 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & -1 & 1 & 0 \\ 2 & 2 & -1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} A \quad \begin{cases} R_4' \leftrightarrow R_4 - R_1 \\ R_3' \leftrightarrow R_3 - 2R_2 \end{cases}$$

$$\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & -1 & 0 \\ -1 & -1 & 1 & 0 \\ 2 & 2 & -1 & 0 \\ 1 & 2 & -1 & 1 \end{bmatrix} A \quad \begin{cases} R_4' = R_4 + R_3 \\ R_1' = R_1 - R_2 \end{cases}$$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & -3 & 1 & -2 \\ -1 & -1 & 1 & 0 \\ -1 & -4 & 2 & -3 \\ 1 & 2 & -1 & 1 \end{bmatrix} A \quad \begin{cases} R_1' = R_1 - 2R_4 \\ R_3' = R_3 - 3R_4 \end{cases}$$

$$I = A^{-1} A$$

$$\therefore A^{-1} = \begin{bmatrix} 0 & -3 & 1 & -2 \\ -1 & -1 & 1 & 0 \\ -1 & -4 & 2 & -3 \\ 1 & 2 & -1 & 1 \end{bmatrix}$$

Rank and Nullity of a matrix:-

The maximum order of the non-singular square sub-matrix of A is called the rank of A . The mtr A is said to be of rank n , if and only if it has at least one nonsingular square sub-mtr of order n and all square submatrices of $(n+1)$ and higher orders are singular. The rank of a mtr A is denoted by $\text{rank}(A)$.

If A is a square mtr of order n , then $n - \text{rank}(A)$ is called the nullity of the mtr A and denoted by $N(A)$.

Remarks:-

1. If I is a unit mtr of order n , $\text{rank}(I) = n$.
2. If A is of order $m \times n$, then $\text{rank}(A) \leq m$ and $\leq n$.
3. If A' is the transpose of A , $\text{rank}(A') = \text{rank}(A)$.

Ex. 1. S.T. the rank of a skew-symmetric mtr can't be 1.

Sol. For a skew-symmetric mtr, the elements of the leading diagonal are all zero. If one element is non-zero, say x , then we have a minor of the form

$$\begin{vmatrix} 0 & x \\ -x & 0 \end{vmatrix} \neq 0$$

Therefore rank of the mtr is ≥ 2 , if all entries are zero then rank is 0.

Ex. 2. Find the rank of the mtrix A, where $A = \begin{bmatrix} 2 & 1 & -1 \\ 0 & 3 & -2 \\ 2 & 4 & -3 \end{bmatrix}$.

Sol. $|A| = 2(-9+8) + 2(-3+4) = 0$
 But $\begin{vmatrix} 2 & 1 \\ 0 & 3 \end{vmatrix} \neq 0$, so rank (A) = 2.

Normal form of a matrix:-

Theorem:- By means of elementary transformations every mtrix A of order $m \times n$ and rank $r (> 0)$ can be reduced to the following form:

- (i) $\left[\begin{array}{c|c} I_r & 0 \\ \hline 0 & 0 \end{array} \right]$ (ii) $\begin{bmatrix} I_r \\ 0 \end{bmatrix}$ (iii) $[I_r | 0]$ (iv) $[I_r]$.

Ex. Reduce the mtrix A to its normal form, where $A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$ and hence determine its rank.

Solution:-

$$\begin{aligned} & \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix} \\ & \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} & \begin{array}{l} R_2' \leftrightarrow R_2 - R_1 \\ R_3' \leftrightarrow R_3 - 3R_1 \end{array} \\ & \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} & R_3' \leftrightarrow R_3 - R_2 \\ & \sim \begin{bmatrix} 1 & 0 & -1 & -6 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} & R_1' \leftrightarrow R_1 - R_2 \\ & \sim \begin{bmatrix} 1 & 0 & 0 & -6 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} & \begin{array}{l} C_3' \leftrightarrow C_3 + C_1 \\ C_3' \leftrightarrow C_3 - 2C_2 \end{array} \\ & \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} & \begin{array}{l} C_4' \leftrightarrow C_4 + 6C_1 \\ C_4' \leftrightarrow C_4 - 5C_2 \end{array} \end{aligned}$$

Hence the normal form of A is $\left[\begin{array}{c|c} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$ and rank (A) = 2.

WORKED EXAMPLES:-

1. If $r(A)$ denotes rank of a mtrx A , then $r(AB)$ is
(a) $r(A)$ (b) $r(B)$ (c) $\leq \min[r(A), r(B)]$ (d) $> \min[r(A), r(B)]$

Sol. $r(AB) \leq \min[r(A), r(B)]$

e.g. $A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$AB = \begin{bmatrix} 7 & 10 \\ 7 & 10 \end{bmatrix}$ $r(A) = 1, r(B) = 2.$

$r(AB) = 1 \leq \min[r(A), r(B)].$

2. Show that $r(A') = r(A^*) = r(A).$

Sol. The transpose of a mtrx is obtained by interchanging rows into columns into rows, and clearly this change does not alter the values of the determinants of minors. Hence

$r(A') = r(A).$

Now assume that the value of a minor of A with complex elements be $a+ib$. Then the value of the corresponding minor of the conjugate mtrx of A be $a-ib$.

in case $a+ib = 0$ then $a-ib = 0$.

in case $a+ib \neq 0$ then $a-ib \neq 0$.

Hence $r(A^*) = r(A) = r(A').$

3. If A is an $(n \times 1)$ non-zero mtrx and B is a $(1 \times n)$ non-zero mtrx, then show that $r(AB) = 1$.

Sol. Let $A = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{n1} \end{bmatrix}$ and $B = [b_{11} \ b_{12} \ \dots \ b_{1n}]$.

Then $AB = \begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} & \dots & a_{11}b_{1n} \\ a_{21}b_{11} & a_{21}b_{12} & \dots & a_{21}b_{1n} \\ \vdots & \vdots & \dots & \vdots \\ a_{n1}b_{11} & a_{n1}b_{12} & \dots & a_{n1}b_{1n} \end{bmatrix}$

AB is non-zero and there will be at least one non-zero minor of order 1.

Hence, $r(AB) = 1$ because all 2nd and higher order minors are all zero here.

4. Find the rank of the matrix $A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & 1 \\ 2 & 0 & -3 & 2 \\ 3 & 3 & 0 & 3 \end{bmatrix}$

Solution:-

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 3 & -2 & 1 \\ 2 & 0 & -3 & 2 \\ 3 & 3 & 0 & 3 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 3 & -2 & 0 \\ 2 & 0 & -3 & 0 \\ 3 & 3 & 0 & 0 \end{bmatrix} \quad c_4' \leftrightarrow c_4 - c_1$$

$\therefore \text{rank}(A) = \text{No. of LIN columns in } A$

$= 3.$

5. Reduce the mtrx A to its normal form, where and hence find the rank of the mtrx.

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

Solution:-

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$R_4' \leftrightarrow R_4 - (R_1 + R_2)$$

$$\sim \begin{bmatrix} 0 & 1 & -3 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$C_1' \leftrightarrow c_1 - (c_2 + c_4)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & -3 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$C_2' = c_1 + c_2$$

5. Reduce the matrix A to its normal form, where

$$A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 2 & 2 & 5 \\ 3 & 4 & 5 & 2 \end{bmatrix}$$

and hence determine its rank.

Sol. To reduce a matrix into its normal form, let us use congruent row and column operations.

$$A \sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 2 & 2 & 5 \\ 3 & 4 & 5 & 2 \end{bmatrix} \quad \text{By } R_{21}(-1)$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } R_{31}(-3)$$

$$\sim \begin{bmatrix} 1 & 0 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{21}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{31}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix} \quad \text{By } C_{41}(1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } R_{32}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } C_{32}(-1)$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{By } C_{42}(-5)$$

Hence the normal form of A is $\left[\begin{array}{c|c} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$ and $\text{rank}(A) = 2$.

6. Reduce the matrix A to its normal form, where

$$A = \begin{bmatrix} 0 & 1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

and hence find the rank of the matrix.

Solution:-

By performing the operation R_{12} , we have

$$A \sim \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 3 & 1 & 0 & 2 \\ 1 & 1 & -2 & 0 \end{bmatrix}$$

By $R_{31}(-3)$,
 $R_{41}(-1)$

$$A \sim \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \end{bmatrix}$$

By $C_{31}(-1)$,
 $C_{41}(-1)$

$$A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \\ 0 & 1 & -3 & -1 \end{bmatrix}$$

By $R_{32}(-1)$,
 $R_{42}(-1)$

$$A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

By $C_{32}(3)$, $C_{42}(1)$, $A \sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

which is of the form $\left[\begin{array}{c|c} I_2 & 0 \\ \hline 0 & 0 \end{array} \right]$; hence $\text{rank}(A) = 2$.

System of Linear Equations

1. The equations $x - y + 2z = 4$
 $3x + y + 4z = 6$
 $x + y + z = 1$ have

- (A) Unique solution (B) Infinite solutions (C) No solution (D) None.

Sol. \rightarrow (B) $[A|b] = \left[\begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 3 & 1 & 4 & 6 \\ 1 & 1 & 1 & 1 \end{array} \right]$

$$\sim \left[\begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 0 & 4 & -2 & -6 \\ 0 & 2 & -1 & -3 \end{array} \right]$$

$$\sim \left[\begin{array}{ccc|c} 1 & -1 & 2 & 4 \\ 0 & 4 & -2 & -6 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$\therefore \text{rank}[A|b] = \text{rank}(A) = 2 < 3$
 \therefore it has infinite solutions.

2. The system of linear equations $x + y + z = 2$, $2x + y - z = 3$,
 $3x + 2y + kz = 4$ has a unique solution if

- (A) $k=0$ (B) $k \neq 1$ (C) $k=1$ (D) $k \neq 0$.

Sol. $[A|b] = \left[\begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 2 & 1 & -1 & 3 \\ 3 & 2 & k & 4 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & -1 & -3 & -1 \\ 0 & -1 & k-3 & -2 \end{array} \right]$

$$\sim \left[\begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & -1 & -3 & -1 \\ 0 & 0 & k & -1 \end{array} \right]$$

$\therefore k \neq 0$

A.H. method:—

Given system has a unique solution if

$$\begin{vmatrix} 1 & 1 & 1 \\ 2 & 1 & -1 \\ 3 & 2 & k \end{vmatrix} \neq 0$$

$\Rightarrow k \neq 0$

3. The system of equations

$$2x + y = 5$$

$$x - 3y = -1$$

$$3x + 4y = k$$

is consistent, when k is

(A) 1

(B) 2

(C) 5

(D) 10

Sol.

$$(D) [A|B] = \begin{bmatrix} 2 & 1 & 5 \\ 1 & -3 & -1 \\ 3 & 4 & k \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -3 \\ 3 & 4 \end{bmatrix} \sim \begin{bmatrix} 2 & 1 \\ 1 & -3 \\ 3 & 4 \end{bmatrix}$$

$$\text{rank}(A) = 2$$

$$\text{Det}[A|B] = -7k + 70$$

\therefore The system is consistent if

$$\text{Det}[A|B] = 0$$

$$\Rightarrow 7k = 70$$

$$\Rightarrow k = 10.$$

4. S.T. the S.O.E. $\left. \begin{array}{l} x_1 - 2x_2 + x_3 - x_4 + 1 = 0 \\ 3x_1 - 2x_3 + 3x_4 + 4 = 0 \\ 5x_1 - 4x_2 + x_4 + 3 = 0 \end{array} \right\}$

is inconsistent.

Sol. Here, we have

$$A = \begin{bmatrix} 1 & -2 & 1 & -1 \\ 3 & 0 & -2 & 3 \\ 5 & -4 & 0 & 1 \end{bmatrix}, [A|b] = \begin{bmatrix} 1 & -2 & 1 & -1 & -1 \\ 3 & 0 & -2 & 3 & -4 \\ 5 & -4 & 0 & 1 & -3 \end{bmatrix}$$

By elementary transformations, A and $[A|b]$ can be reduced in the following forms:

$$A \sim \begin{bmatrix} 1 & 0 & \frac{1}{6} & 1 \\ 0 & 1 & -\frac{5}{6} & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}, [A|b] \sim \begin{bmatrix} 1 & 0 & \frac{1}{6} & 1 & -4/3 \\ 0 & 1 & -5/6 & 1 & -1/6 \\ 0 & 0 & 0 & 0 & 3 \end{bmatrix}$$

$$\therefore \text{rank}(A) = 2 \text{ but } \text{rank}(A|b) = 3$$

\therefore the equations are inconsistent.

5. Find the rank of the matrix $A = \begin{bmatrix} 1 & a & b & 0 \\ 0 & c & d & 1 \\ 1 & a & b & 0 \\ 0 & c & d & 1 \end{bmatrix}$.

Sol.

$$A \sim \begin{bmatrix} 1 & a & b & 0 \\ 0 & c & d & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\therefore \text{rank}(A) = 2.$$

6. Find the inverse of the matrix $\begin{bmatrix} 1 & 2 & 1 \\ 3 & 2 & 3 \\ 1 & 1 & 2 \end{bmatrix}$

Sol. $A = I_3 A$

Applying E-row transformation to the matrix applying $R_2 \rightarrow R_2 - 3R_1$,
 $R_3 \rightarrow R_3 - R_1$.

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} A$$

$$R_2 \rightarrow -\frac{1}{4}R_2$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{3}{4} & \frac{1}{4} & 0 \\ -1 & 0 & 1 \end{bmatrix} A$$

$$R_1 \rightarrow R_1 - 2R_2, R_3 \rightarrow R_3 + R_2$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} & 0 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix} A$$

$$R_1 \rightarrow R_1 - R_3$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{4} & \frac{3}{4} & -1 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix} A$$

$$\therefore I_3 = BA$$

$$\therefore A^{-1} = B.$$

$$\therefore A^{-1} = B = \begin{bmatrix} -\frac{1}{4} & \frac{3}{4} & -1 \\ \frac{3}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 1 \end{bmatrix}$$

7. Solve: $x_1 - x_2 + x_3 = 2$
 $3x_1 - x_2 + 2x_3 = -6$
 $3x_1 + x_2 + x_3 = -18$

Sol. Here, we have $A = \begin{bmatrix} 1 & -1 & 1 \\ 3 & -1 & 2 \\ 3 & 1 & 1 \end{bmatrix}$ and $B = \begin{bmatrix} 1 & -1 & 1 & 2 \\ 3 & -1 & 2 & -6 \\ 3 & 1 & 1 & -18 \end{bmatrix}$

Now, $|A| = 1(-1-2) + 1(3-6) + 1(3+3) = 0$

Also, $\begin{vmatrix} 1 & -1 \\ 3 & -1 \end{vmatrix} \neq 0$; hence $\text{rank}(A) = 2$.

We now proceed to reduce matrix B to its Echelon form

by $R_{21}(-3), R_{31}(-3)$,

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -1 & -12 \\ 0 & 4 & -2 & -24 \end{bmatrix}$$

By $R_{32}(-2)$,

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 2 & -1 & -12 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

By $R_1(1/2)$

$$B \sim \begin{bmatrix} 1 & -1 & 1 & 2 \\ 0 & 1 & -1/2 & -6 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$\therefore \text{rank}(B) = 2 = \text{rank}(A)$.

Hence the given equations are consistent.

Also the mtr equation becomes

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ -6 \\ 0 \end{bmatrix}$$

$$\therefore \begin{cases} x_1 - x_2 + x_3 = 2 \\ x_2 - 1/2 x_3 = -6 \end{cases} \quad \therefore \begin{cases} x_1 = -1/2 x_3 - 4 \\ x_2 = 1/2 x_3 - 6 \end{cases}$$

and x_1, x_2 can be expressed in terms of x_3 which is arbitrary. Since the rank is 2, two unknowns x_1, x_2 are expressed in terms of x_3 , the system has ~~finite~~ infinite number of solutions.

8. Find two non-singular matrices P and Q such that PAQ is in the normal form $\text{diag}(1, -1, -1)$

$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 3 & 1 & 1 \end{bmatrix}$. Also find the rank of the matrix A.

Solution:-

$$A = I_3 A I_3$$

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & -1 & -1 \\ 3 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

E-operations on the matrix A (left hand side) until it is reduced to the normal form.

Every E-row operation will also be applied to the pre-factor I_3 of the product on the right hand member of the above equation and every column operation to the ^{post-}factor I_3

Applying $R_2 \rightarrow R_2 - R_1, R_3 \rightarrow R_3 - 3R_1$

$$\begin{bmatrix} 1 & 1 & 1 \\ 0 & -2 & -2 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing $C_2 \rightarrow C_2 - C_1, C_3 \rightarrow C_3 - C_1$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & -2 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing $R_2 \rightarrow -\frac{1}{2}R_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & -2 & -2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -3 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing $R_3 \rightarrow R_3 + 2R_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -2 & -1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Performing $C_3 \rightarrow C_3 - C_2$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -2 & -1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} I_2 & | & 0 \\ \hline 0 & | & 0 \end{bmatrix} = PAQ, \text{ where}$$

$$P = \begin{bmatrix} 1 & 0 & 0 \\ \frac{1}{2} & -\frac{1}{2} & 0 \\ -2 & -1 & 1 \end{bmatrix}, Q = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix}$$

$\therefore \text{Rank}(A) = 2.$

EIGEN VALUES & VECTORS

Eigen Values:-

Let $A = [a_{ij}]_{n \times n}$ be any square matrix of order n and λ be an indeterminate.

$[A - \lambda I]$ is called characteristic matrix and

$|A - \lambda I| = 0$ is called characteristic equation and roots of this equation is called the characteristic roots or characteristic values or eigen values or latent roots or proper values of the mtr A .

Note:- The set of the eigen values of A is called the spectrum of A .

Eigen Vectors:- If λ is a characteristic root of an $n \times n$ matrix A , then a non-zero vector \underline{x} such that

$$A\underline{x} = \lambda \underline{x}$$

is called a characteristic vector or eigen vector of A corresponding to the characteristic root λ .

Remark:- 1. λ is a characteristic root of a matrix A if and only if there exists a non-zero vector \underline{x} such that $A\underline{x} = \lambda \underline{x}$.

2. If \underline{x} is a characteristic vector of a matrix A corresponding to the characteristic value λ . Here k is any non-zero scalar, then $k\underline{x}$ is also a characteristic vector of A corresponding to the same characteristic value λ .

3. The characteristic vectors corresponding to distinct characteristic roots of a matrix are linearly independent.

Nature of an eigen value of the special types of matrices:-

1. The eigen value of a Hermitian matrix are all real.
2. The eigen value of a real symmetric mtr are all real.
3. The eigen value of a skew-Hermitian mtr are either pure imaginary or zero.
4. The eigen value of a skew symmetric mtr are either pure imaginary or zero.
5. The eigen values of a unitary matrices & an orthogonal matrix are of unit modulus.

Ex. S.T. the eigen value of a triangular matrix are just the diagonal elements of the matrix.

Sol. Let, $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22} & a_{23} \\ 0 & 0 & a_{33} \end{bmatrix}$ be a triangular mtr of order 3.

$$|A - \lambda I| = \begin{vmatrix} a_{11} - \lambda & a_{12} & a_{13} \\ 0 & a_{22} - \lambda & a_{23} \\ 0 & 0 & a_{33} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow (a_{11} - \lambda)(a_{22} - \lambda)(a_{33} - \lambda) = 0$$

$$\Rightarrow \lambda = a_{11}, a_{22}, a_{33}.$$

EX. 2. Determine the eigen values and eigen vectors of the matrix

$$A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$$

Sol.

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 5-\lambda & 4 \\ 1 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (5-\lambda)(2-\lambda) - 4 = 0$$

$$\Rightarrow (\lambda - 6)(\lambda - 1) = 0$$

$$\therefore \lambda_1 = 6, \lambda_2 = 1$$

Eigen vectors $\vec{x}_1 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ of A corresponding to the eigen value 6.

$$(A - 6I)\vec{x} = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 5-6 & 4 \\ 1 & 2-6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -1 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ by } R_2 \leftrightarrow R_2 + R_1$$

rank of the coefficient matrix = 1, there are $(2-1) = 1$ L.I. solution.

$$4x_2 = x_1$$

$$\therefore x_2 = 1, x_1 = 4$$

$\therefore \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ is an eigen vector of A corresponding to the eigen value 6.

The eigen vectors $\vec{x}_2 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ corresponding to the eigen value 1.

$$(A - 1I)\vec{x} = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 4 & 4 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} 4x_1 + 4x_2 = 0 \\ x_1 + x_2 = 0 \end{cases}$$

$$\therefore x_1 = -x_2$$

$$\text{if } x_2 = 1, x_1 = -1.$$

$\therefore \vec{x}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ is the eigen vectors of A corresponding to the eigen value 1.

So, $\vec{x}_1 = k \begin{bmatrix} 4 \\ 1 \end{bmatrix}$, $\vec{x}_2 = h \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ are the eigen vectors

corresponding to the eigen values 6, 1, respectively, where k, h are any non-zero scalars.

The Cayley-Hamilton theorem:-

Every square matrix satisfies ~~the~~ its characteristic equation.
i.e. if for a square matrix A of order n ,

$$|A - \lambda I| = (-1)^n [\lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_n]$$

then the matrix equation

$$x^n + a_1 x^{n-1} + a_2 x^{n-2} + \dots + a_n I = 0$$

is satisfied by $x = A$,

$$\text{i.e. } A^n + a_1 A^{n-1} + a_2 A^{n-2} + \dots + a_n I = 0.$$

Corollary 1:- If A be a non-singular matrix, $|A| \neq 0$.

Pre-multiplying by A^{-1}

$$A^{n-1} + a_1 A^{n-2} + a_2 A^{n-3} + \dots + a_{n-1} I + a_n A^{-1} = 0$$

$$\text{or, } A^{-1} = - \left(\frac{1}{a_n} \right) (A^{n-1} + a_1 A^{n-2} + \dots + a_{n-1} I)$$

Corollary 2:- If m be a positive integer such that $m \geq n$, then multiplying the results by A^{m-n} .

$$A^m + a_1 A^{m-1} + \dots + a_n A^{m-n} = 0.$$

Eigen values and Eigen vectors:-

If V is a vector space over the field F and T is a linear operator on V . An eigen value of T is a scalar c in F such that there is a non-zero vector, $\alpha \in V$ with $T\alpha = c\alpha$.

If c is an eigen value of T , then

(a) Any α such that $T\alpha = c\alpha$ is called eigen vector of T associated with the eigen value c ;

(b) The collection of all α such that $T\alpha = c\alpha$ is called the eigen space associated with c .

Eigen value of matrix A over F :- If A is an $n \times n$ matrix over the field F , an eigen value of A over F is a scalar c in F such that the matrix $(A - cI)$ is singular (not invertible).

Diagonalisable:- If T is a linear operator on the finite dimensional space V . Then T is diagonalizable if there is a basis for V each vector of which is an eigen vector of T .

Eigen polynomial:-

$$f(c) = |A - cI|.$$

Some Important Theorem:-

1. If T is a linear operation on a finite dimensional space V and c is any scalar, then followings are equivalent:
 - (a) c is an eigen value of T
 - (b) The operator $(T - cI)$ is singular (not invertible)
 - (c) $\det(T - cI) = 0$.
2. Similar matrices have the same eigen ~~matrix~~ polynomial.
3. If $T\alpha = c\alpha$ and F is any polynomial, then $F(T)\alpha = F(c)\alpha$
4. Suppose T is a linear operator on the finite dimensional space V ; c_1, \dots, c_k are k -distinct eigen values of T and W is the space of the eigen vectors associated with the eigen value c_i . If $W = W_1 + W_2 + \dots + W_k$, then

$$\dim(W) = \dim(W_1) + \dim(W_2) + \dots + \dim(W_k).$$

In fact, if B_i is an ordered basis for W_i , then $B = (B_1, \dots, B_k)$ is an ordered basis for W .

5. If T is a linear operator on a finite dimensional space V and W_i is a null space of $(T - c_i I)$. The followings are equivalent:
 - (i) T is diagonalizable
 - (ii) The eigen polynomial for T is $F = (x - c_1)^{d_1} (x - c_2)^{d_2} \dots (x - c_k)^{d_k}$, with $\dim(W_i) = d_i, i = 1(1)k$.
 - (iii) $\dim V = \dim(W_1) + \dim(W_2) + \dots + \dim(W_k)$.

Theorem:- If α is a characteristic vector of T corresponding to the eigen value λ , then $k\alpha$ is also a ch. vector of T corresponding to the same ch. value λ . Here k is any non-zero scalar.

Proof:- Since α is a characteristic vector of T corresponding to the ch. value λ , therefore, ~~$\alpha \neq 0$~~ $\alpha \neq 0$ and

$$T(\alpha) = \lambda \alpha \quad ; \text{ let, } k \text{ be any non-zero scalar.}$$

$$T(k\alpha) = kT(\alpha) = k(\lambda \alpha) = \lambda(k\alpha).$$

$\therefore k\alpha$ is a characteristic vector of T corresponding to the characteristic value λ .

Thus, corresponding to a ch. value λ , there may correspond more than one characteristic vectors.

Theorem:- If α is a ch. vector of T , then α can't correspond to more than one ch. values of T .

Proof:- $T\alpha = c_1 \alpha$ and $T\alpha = c_2 \alpha$; where c_1, c_2 are two distinct ch. values of T .

$$\begin{aligned} c_1 \alpha &= c_2 \alpha \\ \Rightarrow (c_1 - c_2) \alpha &= 0 \quad [\because \alpha \neq 0] \\ \Rightarrow c_1 - c_2 &= 0 \\ \Rightarrow c_1 &= c_2. \end{aligned}$$

So, a ch. vector of a matrix, can't correspond to more than one characteristic value of that mtr.

Theorem: Let T be a linear operator on an n -dimensional vector space V and A be the matrix of T relative to any ordered basis B . Then a vector α in V is an eigenvector of T corresponding to its eigenvalue c if and only if its coordinate vector \underline{x} relative to the basis B is an eigen-vector of A corresponding to its eigenvalue c .

Proof: We have $[T - cI]_B = [T]_B - c[I]_B$
 $= A - cI$.

If $\alpha \neq 0$, then the coordinate vector \underline{x} of α is also non-zero.
 Now, $[(T - cI)(\alpha)]_B = [T - cI]_B [\alpha]_B$
 $= (A - cI)\underline{x}$

$$\therefore (T - cI)(\alpha) = 0 \text{ iff } (A - cI)\underline{x} = 0$$

$$\text{on, } T(\alpha) = c\alpha \text{ iff } A\underline{x} = c\underline{x}.$$

on, α is an eigen-vector of T iff \underline{x} is an eigen vector of A .

Ex.1. Let V be an n -dimensional vector space over F . What is the ch. polynomial of (i) the identity operator on V ,
 (ii) the zero operator on V .

Sol. Let B be any ordered basis for V .

(i) If I is the identity operator on V , then $[I]_B = I$.
 The characteristic polynomial of I , $\det(I - xI)$

$$= \begin{vmatrix} 1-x & 0 & \dots & 0 \\ 0 & 1-x & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1-x \end{vmatrix} = (1-x)^n.$$

(ii) If \hat{O} is the zero operator on V , then $[\hat{O}]_B = \hat{O}$, i.e. the null matrix of order n , then the ch. polynomial of \hat{O} is

$$\det(\hat{O} - xI) = \begin{vmatrix} -x & 0 & \dots & 0 \\ 0 & -x & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & -x \end{vmatrix} = (-1)^n x^n.$$

Ex.2. If $c \in F$ is a ch. value of a linear operator T on a vector space $V(F)$, then for any polynomial $P(X)$ over F , $P(c)$ is a ch. value of $P(T)$.

Sol. Since c is a ch. value of T , therefore \exists a non-zero vector $\underline{\alpha}$ in V \ni

$$\begin{aligned} T\underline{\alpha} &= c\underline{\alpha} \\ \Rightarrow T(T\underline{\alpha}) &= T(c\underline{\alpha}) \\ \Rightarrow T^2\underline{\alpha} &= cT(\underline{\alpha}) = c^2\underline{\alpha} \\ \therefore c^2 &\text{ is a ch. value of } T^2. \end{aligned}$$

Repeating this process k times, we get

$$T^k \underline{\alpha} = c^k \underline{\alpha}.$$

$\therefore c^k$ is a ch. value of T^k , where k be any positive integer.

Let $p(x) = a_0 + a_1x + a_2x^2 + \dots + a_mx^m$, where $a_i \in F$.

Then $p(T) = a_0I + a_1T + a_2T^2 + \dots + a_mT^m$.

$$\begin{aligned} \text{We have } [P(T)](\alpha) &= (a_0I + a_1T + \dots + a_mT^m)(\alpha) \\ &= a_0I\alpha + a_1T(\alpha) + \dots + a_mT^m(\alpha) \\ &= a_0\alpha + a_1(c\alpha) + \dots + a_m(c^m\alpha) \\ &= (a_0 + c a_1 + \dots + c^m a_m)\alpha. \end{aligned}$$

$\therefore P(c) = a_0 + c a_1 + \dots + a_m c^m$ is a ch. value of $P(T)$.

Ex. 3. Find all (complex) ch. values and ch. vectors of the following matrix $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$.

Sol.

$$|A - xI| = \begin{vmatrix} -x & 1 \\ 0 & -x \end{vmatrix} = 0$$

$$\Rightarrow x^2 = 0 \Rightarrow x = 0$$

$\therefore 0$ is the only ch. value of A .

Let x_1, x_2 be the components of the ch. vector corresponding to this ch. value 0 .

$$\text{Let } \tilde{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$\text{Now, } [A - 0 \cdot I] \tilde{x} = \tilde{0}$$

$$\Rightarrow \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{i.e. } x_2 = 0$$

Let $x_1 = k$; where k is any non-zero complex number.

$\therefore \tilde{x} = \begin{bmatrix} k \\ 0 \end{bmatrix}$ is the ch. vector corresponding to the eigen value $\lambda = 0$, where k is any non-zero complex no.

WORKED EXAMPLES:-

1. The eigen values of the matrix $\begin{bmatrix} 1 & 1 & 3 \\ 1 & 5 & 1 \\ 3 & 1 & 1 \end{bmatrix}$ is

- (A) 2, 3, 6 (B) 2, 6, 7 (C) -2, 3, 6 (D) None.

Sol. (C) $|A - \lambda I| = 0$

$$\Leftrightarrow \begin{vmatrix} 1-\lambda & 1 & 3 \\ 1 & 5-\lambda & 1 \\ 3 & 1 & 1-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 5-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 \\ 3 & 1 \end{vmatrix} + 3 \begin{vmatrix} 1 & 5-\lambda \\ 3 & 1 \end{vmatrix}$$

$$= (\lambda+2)(\lambda-3)(\lambda-6) = 0$$

$\Rightarrow \lambda = -2, 3, 6.$

2. Find the eigen values of $(A^4 + 3A - 2I)$, where

$A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ are

- (A) 2, 3, 20 (B) 2, 2, 2 (C) 2, 2, 20 (D) 20, 20, 2

Sol. (C) $A^2 = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix}$

$A^4 = \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 3 \\ 0 & 4 & 3 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 15 & 15 \\ 0 & 16 & 15 \\ 0 & 0 & 1 \end{bmatrix}$

Now, $B = A^4 + 3A - 2I$

$$= \begin{bmatrix} 1 & 15 & 15 \\ 0 & 16 & 15 \\ 0 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 3 & 3 & 3 \\ 0 & 6 & 3 \\ 0 & 0 & 3 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 18 & 18 \\ 0 & 20 & 18 \\ 0 & 0 & 2 \end{bmatrix}$$

Then the eigen values of $|B - \lambda I| = 0$

$$\Leftrightarrow \begin{vmatrix} 2-\lambda & 18 & 18 \\ 0 & 20-\lambda & 18 \\ 0 & 0 & 2-\lambda \end{vmatrix} = 0$$

$\Rightarrow \lambda = 2, 20, 2.$

3. Find the eigen values of A^4 , where $A = \begin{pmatrix} 1 & 0 & -1 \\ 9 & 4 & 1 \\ 3 & 1 & 1 \end{pmatrix}$.

Sol.

$$A = \begin{pmatrix} 1 & 0 & -1 \\ 9 & 4 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

then the eigen values of the matrix can be determined from the ch. equation

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 0 & -1 \\ 9 & 4-\lambda & 1 \\ 0 & 1 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (1-\lambda)(\lambda-2)(\lambda-3) = 0$$

$$\Rightarrow \lambda = 1, 2, 3.$$

\therefore the eigen values of A are: 1, 2, 3.

So, the eigen values of A^4 are: $1^4, 2^4, 3^4$, i.e. 1, 16, 81.

4. Use Cayley Hamilton theorem, find the inverse of $A = \begin{bmatrix} -1 & 1 & 1 \\ 3 & 1 & -1 \\ 2 & 2 & 1 \end{bmatrix}$

Sol.

$$|A - \lambda I| = 0$$

$$\Rightarrow \begin{vmatrix} -1-\lambda & 1 & 1 \\ 3 & 1-\lambda & -1 \\ 2 & 2 & 1-\lambda \end{vmatrix} = 0$$

$$\Rightarrow -\lambda^3 + \lambda^2 - 4\lambda - 4 = 0$$

$$\Rightarrow A^3 - A^2 + 4A + 4I = 0$$

$$\Rightarrow A^{-1} = \frac{-A^2 + A + 4I}{4}$$

$$= \frac{1}{4} \left[- \begin{bmatrix} 6 & 2 & -1 \\ -2 & 2 & 1 \\ 6 & 6 & 1 \end{bmatrix} + \begin{bmatrix} -1 & 1 & 1 \\ 3 & 1 & -1 \\ 2 & 2 & 1 \end{bmatrix} + \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} \right]$$

$$= \frac{1}{4} \begin{bmatrix} -3 & -1 & 2 \\ 5 & 3 & -2 \\ 4 & -4 & 4 \end{bmatrix}$$

5. If λ_1 and λ_2 are the values of λ for which $\begin{vmatrix} 1 & \lambda & 0 \\ \lambda & 2 & 1 \\ 0 & 1 & 1 \end{vmatrix} = 0$, then $\lambda_1 + \lambda_2$ equals (A) -1 (B) 0 (C) 1 (D) 2.

Sol. (B) $\begin{vmatrix} 1 & \lambda & 0 \\ \lambda & 2 & 1 \\ 0 & 1 & 1 \end{vmatrix} = 0$

$$\Rightarrow 1(2-1) - \lambda(\lambda) = 0$$

$$\Rightarrow \lambda^2 = 1 \quad \text{i.e. } \lambda_1 + \lambda_2 = 1 - 1 = 0.$$

$$\Rightarrow \lambda = \pm 1$$

6. Find the characteristic roots and corresponding characteristic vectors for each of the following matrix $A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$

Sol. The characteristic equation is

$$|A - \lambda I| = \begin{vmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{vmatrix} = -\lambda^3 + 18\lambda^2 - 45\lambda = 0$$

$$\Rightarrow \lambda(\lambda-3)(\lambda-15) = 0$$

$\Rightarrow \lambda = 0, 3, 15$ are the 3 ch. roots of the mtX A.

If \underline{x} is a characteristic vector corresponding to the ch. root 0, then we have

$$A\underline{x} = \lambda\underline{x}$$

$$\Rightarrow [A - \lambda I]\underline{x} = \underline{0}$$

$$\Rightarrow \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow 8x_1 - 6x_2 + 2x_3 = 0, \quad -6x_1 + 7x_2 - 4x_3 = 0, \quad 2x_1 - 4x_2 + 3x_3 = 0$$

Let $x_1 = 1$, then $x_2 = 2, x_3 = 2$.

$\therefore \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$ is a ch. vector corresponding to the

It may similarly be shown by considering the equation

$$(A - 3I)\underline{x} = \underline{0},$$

$$(A - 15I)\underline{x} = \underline{0},$$

that the ch. vectors corresponding to the ch. roots 3 and 15 are arbitrary non-zero multiples of the vectors

$$\begin{bmatrix} 2 \\ 1 \\ -2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

7. Find the eigen value of the mtX $\begin{bmatrix} 1 & 0 & 0 & -a/2 \\ 0 & 1 & 0 & -a/2 \\ 0 & 0 & 1 & -a/2 \\ 0 & 0 & 0 & a \end{bmatrix}$.

Sol.

$$\det [A - \lambda I] = 0$$

$$\Rightarrow (1-\lambda)(1-\lambda)(1-\lambda)(a-\lambda) = 0$$

$\Rightarrow \lambda = 1, 1, 1, a$ are the eigen values.

8. Let $M = \begin{pmatrix} 1 & 1+i & 2-i \\ 1-i & 2 & 3+i \\ 2+i & 3-i & 3 \end{pmatrix}$. If $B = \begin{pmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ x_3 & y_3 & z_3 \end{pmatrix}$, where $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$, $\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$ and $\begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix}$ are LIN eigenvectors of M , then the main diagonal of the matrix $B^{-1}MB$ has
- (A) exactly one real entry (B) exactly two real entries
 (C) exactly 3 real entries (D) no real entries

Sol.

$$M^T = M^*$$

$\Rightarrow M$ is a Hermitian matrix

Since B is invertible mtr.

$\Rightarrow B^{-1}MB$ is a diagonal mtr whose diagonal entries are eigenvalues of M .

We know the eigen values of Hermitian mtr are real.

\Rightarrow all three eigen values are real.

9. Let P be a 3×3 mtr \ni for some c , the linear system $Px = c$ has infinite number of solutions. Which one of the following is TRUE?

- (A) The linear system $Px = b$ has infinite no. of solutions $\forall b$.
 (B) $\text{Rank}(P) = 3$ (C) $\text{Rank}(P) \neq 1$ (D) $\text{Rank}(P) \leq 2$.

Sol. (D) $\text{rank}(P) < n \Rightarrow Px = b$ has infinite no. of solutions
 $\therefore \text{Rank}(P) \leq 2$.

10. Let P be a 2×2 mtr $\ni P^{102} = 0$. Then
 (A) $P^2 = 0$ (B) $(1-P)^2 = 0$ (C) $(1+P)^2 = 0$ (D) $P = 0$

Sol. (A) Since P is mtr of order 2 so its ch. equation is of order 2. So P^{102} is equal to 0 iff $P^2 = 0$.

11. Let A be an $n \times n$ matrix $\ni P^{-1}AP > 0$ for every non-zero invertible mtr P where P is also an $n \times n$ mtr. Which of the following is TRUE?

- (A) All eigen values of A are negative (B) All eigen values of A are positive.

Sol. (B) Since given that for mtr A , $P^{-1}AP > 0$.

Here $P^{-1}AP$ is a diagonal mtr whose diagonal elements are eigen values of matrix A . But $P^{-1}AP > 0$ shows the eigen values of A are all positive.

12) Let $P = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$, the eigenvectors corresponding to the eigenvalues i and $-i$ are respectively

- (A) $\begin{pmatrix} 1 \\ i \end{pmatrix}$ and $\begin{pmatrix} -1 \\ i \end{pmatrix}$ (B) $\begin{pmatrix} 1 \\ i \end{pmatrix}$ and $\begin{pmatrix} -1 \\ -i \end{pmatrix}$ (C) $\begin{pmatrix} -1 \\ i \end{pmatrix}$ and $\begin{pmatrix} i \\ -i \end{pmatrix}$ (D) $\begin{pmatrix} i \\ 1 \end{pmatrix}$ and $\begin{pmatrix} 1 \\ i \end{pmatrix}$

Sol.

$$\lambda_1 = i, \lambda_2 = -i$$

$$(P - \lambda_1 I) \underline{x} = 0$$

$$\Rightarrow \begin{bmatrix} 0-i & 1 \\ -1 & -i \end{bmatrix} \underline{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} -x_1 i + x_2 = 0 \\ -x_1 - i x_2 = 0 \end{cases}$$

$$x_1 = 1, x_2 = i$$

$\therefore \begin{bmatrix} 1 \\ i \end{bmatrix}$ is the eigen vector corresponding to the eigen value i .

$$(P - \lambda_2 I) \underline{x}' = 0$$

$$\Rightarrow \begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow \begin{cases} i x_1 + x_2 = 0 \\ -x_1 + i x_2 = 0 \end{cases}$$

$$\therefore x_1 = -1, x_2 = i$$

$\therefore \begin{bmatrix} -1 \\ i \end{bmatrix}$ is the eigenvector corresponding to the eigen value $-i$.

13) Let P, M, B be $n \times m$ matrices \ni M and N are non-singular. If \underline{x} is an eigen vector of P corresponding to the eigen value λ , then an eigen vector of $N^{-1} M P M^{-1} N$ corresponding to the eigen value λ is

- (A) $M N^{-1} \underline{x}$ (B) $M^{-1} N \underline{x}$ (C) $N M^{-1} \underline{x}$ (D) $N^{-1} M \underline{x}$

Sol. (C) Since λ is eigenvalue of P and \underline{x} be the eigen vector corresponding to it.

$$\Rightarrow P \underline{x} = \lambda \underline{x}$$

$$N^{-1} M P M^{-1} N (N^{-1} M \underline{x}) = N^{-1} M P M^{-1} (N N^{-1}) M \underline{x}$$

$$= N^{-1} M P M^{-1} M \underline{x}$$

$$= N^{-1} M P (M^{-1} M) \underline{x}$$

$$= N^{-1} M P \underline{x}$$

$$= N^{-1} M \lambda \underline{x}$$

$$= \lambda N^{-1} M \underline{x}$$

$\therefore N^{-1} M \underline{x}$ is eigen vector corresponding to λ .

14) Let $P = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$, then

- (A) P has two linearly independent eigenvectors (B) P has an eigen vectors
 (C) P is non-singular (D) \exists a non-singular $S \exists S^{-1}PS$ is a diagonal mtr

sol.

(D)

14) Let P be an $n \times n$ idempotent mtr, that is $P^2 = P$, which of the following is FALSE?

- (A) P^T is idempotent
 (B) The possible eigenvalues of P are 0 and 1.
 (C) The non-diagonal entries of P can be zero.
 (D) There are infinite no. of $n \times n$ non-singular matrices that are idempotent

Solution:-

(A) Since P is idempotent matrix, i.e. $P^2 = P$, then P^T is also idempotent, as $(P^2)^T = P^T \Rightarrow (P^T)^2 = P^T$.

$P^2 = P \Rightarrow P(P-I) = 0 \Rightarrow$ eigen values of P are 0 and 1.
 the non-diagonal entries of an idempotent mtr can be zero,
 e.g. $P = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$, $P^2 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = P$.

So, (D) is FALSE.

15) Let A and B are any arbitrary square matrices of order 2. Then show that AB and BA have same eigen values but may have different eigen vectors.

Solution:- Let us take an example.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}, B = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$AB = \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix}$$

$$|AB - \lambda I| = 0 \Rightarrow (1-\lambda)(2-\lambda) = 0$$

$$\Rightarrow \lambda^2 - 3\lambda = 0$$

$$\Rightarrow \lambda(\lambda - 3) = 0$$

$$\Rightarrow \lambda = 0, \lambda = 3.$$

For $\lambda = 0$, $[AB - 0 \cdot I] \vec{x} = \vec{0}$

$$\Rightarrow \begin{bmatrix} 1 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\therefore x_1 + x_2 = 0$$

$$\therefore x_1 = 1, x_2 = -1$$

$\therefore \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ be an eigen vector corresponds to $\lambda = 0$.

For $\lambda = 3$,

$$[AB - 3 \cdot I] \vec{x} = \vec{0}$$

$$\Rightarrow \begin{bmatrix} 1-3 & 1 \\ 2 & 2-3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow -2x_1 + x_2 = 0, 2x_1 - x_2 = 0$$

$$\therefore x_2 = 2, x_1 = 1$$

$\therefore \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ is the eigen vector.

Here $BA = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$

$\therefore |BA - \lambda I| = 0$

$\Rightarrow \begin{vmatrix} 1-\lambda & 2 \\ 1 & 2-\lambda \end{vmatrix} = 0$

$\Rightarrow \lambda = 0, 3.$

For $\lambda = 0$, $[BA - 0 \cdot I] \underline{x} = \underline{0}$

$\Rightarrow \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$\Rightarrow x_1 + 2x_2 = 0$

$\Rightarrow x_1 = -2x_2$

$\therefore x_2 = -1/2, x_1 = 1$

$\therefore \begin{bmatrix} 1 \\ -1/2 \end{bmatrix}$ be the eigenvector corresponding to $\lambda = 0$.

For $\lambda = 3$, $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ be the eigenvector corresponding to $\lambda = 3$.

$\therefore AB$ & BA have same eigen values but not same eigen vectors.

16) A real 3×3 mtr M has eigen values $+1$ and 2 . s.t.
 (i) M is invertible (ii) $M^3 - 2M^2$ is singular (iii) M is diagonalisable.

Sol. We have a mtr M whose 3 eigenvalues are $+1, -1$ and 2 .
 its ch. equation can be given as

$(M+I)(M-I)(M-2I) = 0$
 $\Rightarrow (M^2-I)(M-2I) = 0$

$\Rightarrow M^3 - 2M^2 = M - 2I$

(i) By the properties of eigenvalues:
 determinant of mtr = multiplication of eigenvalues
 $|M| = (-1) \times (1) \times (2)$

$|M| = -2$
 here $|M| \neq 0 \Rightarrow M$ is invertible.

(ii) $|M^3 - 2M^2| = |M - 2I|$

Since $|M| = -2$

$|M - 2I| = 0$

$\Rightarrow |M^3 - 2M^2| = 0$

$\Rightarrow M^3 - 2M^2$ is singular.

(iii) Since M having 3 distinct eigenvalues, then the ch. vectors corresponding to distinct characteristics roots of a mtr are LIN.

And an $n \times n$ mtr is diagonalisable if and only if it possesses n linearly independent eigenvectors.

$\Rightarrow M$ is diagonalisable.